

Statistical Learning Theory

Fundamentals

Miguel A. Vezanzones

Grupo Inteligencia Computacional
Universidad del País Vasco

Outline

- 1 Introduction
 - Learning problem
 - Statistical learning theory

- 2 Minimizing the risk functional on the basis of empirical data
 - The pattern recognition problem
 - The regression problem
 - The density estimation problem (Fisher-Wald setting)
 - Induction principles for minimizing the risk functional on the basis of empirical data

Approaches to the learning problem

- Learning problem: the problem of choosing the desired dependence on the basis of empirical data.
- Two approaches:
 - To choose an approximating function from a given set of functions.
 - To estimate the desired stochastic dependences (densities, conditional densities, conditional probabilities).

First approach

To choose an approximating function from a given set of functions

- It's a problem rather general.
- Three subproblems: pattern recognition, regression, density estimation.
- Based on the idea that the quality of the chosen function can be evaluated by a risk functional.
- Problem of minimizing the risk functional on the basis of empirical data.

Second approach

To estimate the desired stochastic dependences

- Using estimated stochastic dependence, the pattern recognition, the regression and the density estimation problems can be solved as well.
- Requires solution of integral equations for determining these dependences when some elements of the equation are unknown.
- It gives much more details but it's an ill-posed problem.

General problem of learning from examples

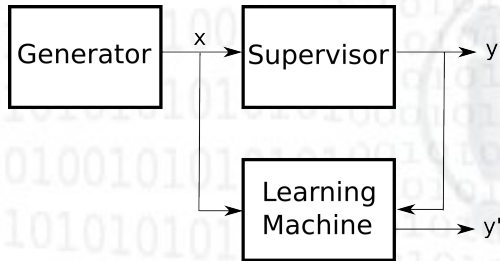


Figure: A model of learning by examples

Generator

- The Generator, G , determines the environment in which the Supervisor and the Learning Machine act.
- Simplest environment: G generates the vector $\mathbf{x} \in \mathbf{X}$ independently and identically distributed (i.i.d.) according to some unknown but fixed probability distribution function, $F(\mathbf{x})$.

Supervisor

- The Supervisor, S , transforms the input vectors \mathbf{x} into the output values y .
- Supposition: S returns the output y on the vector \mathbf{x} according to a conditional distribution function, $F(y|\mathbf{x})$, which includes the case when the supervisor uses some function $y = f(\mathbf{x})$.

Learning Machine

- The Learning Machine, LM , observes the l pairs $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_l, y_l)$, the training set, which is drawn randomly and independently according to a joint distribution function $F(\mathbf{x}, y) = F(y|\mathbf{x})F(\mathbf{x})$.
- Using the training set, LM constructs some operator which will be used for prediction of the supervisor's answer y_i on any specific vector \mathbf{x}_i generated by G .

Two different goals

- 1 To *imitate* the supervisor's operator: try to construct an operator which provides for a given G , the best predictions to the supervisor's outputs.
- 2 To *identify* the supervisor's operator: try to construct an operator which is close to the supervisor's operator.
 - Both problems are based on the same general principles.
 - The learning process is a process of choosing an appropriate function from a given set of functions.

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Functional

- Among the totality of possible functions, one looks for the one that satisfies the given quality criterion in the best possible manner.
- Formally: on the subset Z of the vector space \mathfrak{R}^n , a set of admissible functions $\{g(\mathbf{z})\}$, $\mathbf{z} \in Z$, is given and a functional $R = R(g(\mathbf{z}))$ is defined.
- It's required to find the function $g'(\mathbf{z})$ from the set $\{g(\mathbf{z})\}$ which minimizes the functional $R = R(g(\mathbf{z}))$.

Two cases

- 1 When the set of functions $\{g(\mathbf{z})\}$ and the functional $R(g(\mathbf{z}))$ are explicitly given: calculus of variations.
- 2 When a p.d.f. $F(\mathbf{z})$ is defined on Z and the functional is defined as the mathematical expectation

$$R(g(\mathbf{z})) = \int L(\mathbf{z}, g(\mathbf{z})) dF(\mathbf{z}) \quad (1)$$

where function $L(\mathbf{z}, g(\mathbf{z}))$ is integrable for any $g(\mathbf{z}) \in \{g(\mathbf{z})\}$.

- The problem is then, to minimize (1) when $F(\mathbf{z})$ is unknown but the sample $\mathbf{z}_1, \dots, \mathbf{z}_l$ of observations is available.

Problem definition

- 1 Imitation problem: how can we obtain the minimum of the functional in the given set of functions?
 - 2 Identification problem: what should be minimized in order to select from the set $\{g(\mathbf{z})\}$ a function which will guarantee that the functional (1) is small?
- The minimization of the functional (1) on the basis of empirical data $\mathbf{z}_1, \dots, \mathbf{z}_l$ is one of the main problems of mathematical statistics.

Parametrization

- The set of functions $\{g(\mathbf{z})\}$ will be given in a parametric form $\{g(\mathbf{z}, \alpha), \alpha \in \Lambda\}$.
- The study of only parametric functions is not a restriction on the problem, since the set Λ is arbitrary: a set of scalar quantities, a set of vectors or a set of abstract elements.
- The functional (1) can be rewritten as

$$R(\alpha) = \int Q(\mathbf{z}, \alpha) dF(\mathbf{z}), \quad \alpha \in \Lambda \quad (2)$$

where $Q(\mathbf{z}, \alpha) = L(\mathbf{z}, g(\mathbf{z}, \alpha))$ is called the *loss function*.

The expected loss

- It's assumed that each function $Q(\mathbf{z}, \alpha^*)$ determines the amount of the loss resulting from the realization of the vector \mathbf{z} for a fixed $\alpha = \alpha^*$.
- The expected loss with respect to \mathbf{z} for the function $Q(\mathbf{z}, \alpha^*)$ is determined by the integral

$$R(\alpha) = \int Q(\mathbf{z}, \alpha^*) dF(\mathbf{z}) \quad (3)$$

which is called the *risk functional* or the *risk*.

Problem redefinition

Definition

The problem is to choose in the set $\mathcal{Q}(\mathbf{z}, \alpha)$, $\alpha \in \Lambda$, a function $Q(\mathbf{z}, \alpha_0)$ which minimizes the risk when the probability distribution function is unknown but random independent observations $\mathbf{z}_1, \dots, \mathbf{z}_l$ are given.

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Informal definition

Definition

A supervisor observes occurring situations and determines to which of k classes each one of them belongs. It is required to construct a machine which, after observing the supervisor's classification, carries out the classification approximately in the same manner as the supervisor.

Formal definition

Definition

In a certain environment characterized by a p.d.f. $F(\mathbf{x})$, situation \mathbf{x} appears randomly and independently. the supervisor classifies each situation into one of k classes. We assume that the supervisor carries out this classification by $F(\omega|\mathbf{x})$, where $\omega \in \{0, 1, \dots, k-1\}$.

- Neither $F(\mathbf{x})$ nor $F(\omega, \mathbf{x})$ are known, but they exist.
- Thus, a joint distribution function $F(\omega, \mathbf{x}) = F(\omega|\mathbf{x})F(\mathbf{x})$ exists.

Loss function

- Let a set of functions $\phi(\mathbf{x}, \alpha)$, $\alpha \in \Lambda$, which take only k values $\{0, 1, \dots, k-1\}$ (a set of decision rules) be given.
- We shall consider the simplest loss function:

$$L(\omega, \phi) = \begin{cases} 1 & \text{if } \omega = \phi \\ 0 & \text{if } \omega \neq \phi \end{cases}$$

- The problem of pattern recognition is to minimize the functional

$$R(\alpha) = \int L(\omega, \phi(\mathbf{x}, \alpha)) dF(\omega, \mathbf{x})$$

on the set of functions $\phi(\mathbf{x}, \alpha)$, $\alpha \in \Lambda$, where the p.d.f. $F(\omega, \mathbf{x})$ is unknown but a random independent sample of pairs $(\mathbf{x}_1, \omega_1), \dots, (\mathbf{x}_l, \omega_l)$ is given.

Restrictions

- The problem of pattern recognition has been reduced to the problem of minimizing the risk on the basis of empirical data, where the set of loss functions $Q(\mathbf{z}, \alpha)$, $\alpha \in \Lambda$, is not arbitrary as in the general case.
- The following restrictions are imposed:
 - The vector \mathbf{z} consist of $n+1$ coordinates: coordinate ω (which takes a finite number of values) and n coordinates x^1, x^2, \dots, x^n which form the vector \mathbf{x} .
 - The set of functions $Q(\mathbf{z}, \alpha)$, $\alpha \in \Lambda$ is given by

$$Q(\mathbf{z}, \alpha) = L(\omega, \phi(\mathbf{x}, \alpha)), \quad \alpha \in \Lambda$$

and also takes on only a finite number of values.

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Stochastic dependences

- There exist relationships (stochastic dependences) where to each vector \mathbf{x} there corresponds a number y which we obtain as a result of random trials. $F(y|\mathbf{x})$ expresses that stochastic relationship.
- Estimating the stochastic dependence based on the empirical data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_l, y_l)$ is a quite difficult problem (ill-posed problem).
- However, the knowledge of $F(y|\mathbf{x})$ is often not required and it's sufficient to determine one of its characteristics.

Regression

- The function of conditional mathematical expectation

$$r(\mathbf{x}) = \int y dF(y|\mathbf{x})$$

is called the *regression*.

- Estimate the regression in the set of functions $f(\mathbf{x}, \alpha)$, $\alpha \in \Lambda$, is referred to as the problem of regression estimation.

Conditions

- The problem of regression estimation is reduced to the model of minimizing risk based on empirical data under the following conditions:

$$\int y^2 dF(y, \mathbf{x}) < \infty \quad \int r^2(\mathbf{x}) dF(y, \mathbf{x}) < \infty$$

- On the set $f(\mathbf{x}, \alpha), \alpha \in \Lambda, f(\mathbf{x}, \alpha) \in L_2$, the minimum (if exists) of the functional

$$R(\alpha) = \int (y - f(\mathbf{x}, \alpha))^2 dF(y, \mathbf{x})$$

is attained at:

- The regression function if $r(\mathbf{x}) \in f(\mathbf{x}, \alpha), \alpha \in \Lambda$.
- The function $f(\mathbf{x}, \alpha^*)$ which is the closest to $r(\mathbf{x})$ in the L_2 metric if $r(\mathbf{x}) \notin f(\mathbf{x}, \alpha), \alpha \in \Lambda$.

Demonstration

- Denote $\Delta f(\mathbf{x}, \alpha) = f(\mathbf{x}, \alpha) - r(\mathbf{x})$.
- The functional can be rewritten as:

$$R(\alpha) = \int (y - r(\mathbf{x}))^2 dF(y, \mathbf{x}) + \int (\Delta f(\mathbf{x}, \alpha))^2 dF(y, \mathbf{x}) \\ - 2 \int \Delta f(\mathbf{x}, \alpha) (y - r(\mathbf{x}))^2 dF(y, \mathbf{x})$$

- $\int (y - r(\mathbf{x}))^2 dF(y, \mathbf{x})$ does not depend of α .
- $\int \Delta f(\mathbf{x}, \alpha) (y - r(\mathbf{x}))^2 dF(y, \mathbf{x}) = 0$.

Restrictions

- The problem of estimating the regression may be also reduced to the scheme of minimizing the risk. The following restrictions are imposed:
 - The vector \mathbf{z} consist of $n + 1$ coordinates: coordinate y and n coordinates x^1, x^2, \dots, x^n which form the vector \mathbf{x} . However, the coordinate y as well as the function $f(\mathbf{x}, \alpha)$ may take any value on the interval $(-\infty, \infty)$.
 - The set of functions $Q(\mathbf{z}, \alpha), \alpha \in \Lambda$ is on the form

$$Q(\mathbf{z}, \alpha) = (y - f(\mathbf{x}, \alpha))^2, \quad \alpha \in \Lambda$$

and can take on arbitrary non-negative values.

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Problem definition

- Let $p(\mathbf{x}, \alpha)$, $\alpha \in \Lambda$, be a set of probability densities containing the required density:

$$p(\mathbf{x}, \alpha_0) = \frac{dF(\mathbf{x})}{d\mathbf{x}}$$

- Considering the functional:

$$R(\alpha) = \int \ln p(\mathbf{x}, \alpha) dF(\mathbf{x}) \quad (4)$$

the problem of estimating the density in the L_1 metric is reduced to the minimization of the functional (4) on the basis of empirical data (Fisher-Wald formulation).

Assertions (I)

Functional's minimum

- The minimum of the functional (4) (if it exists) is attained at the functions $p(\mathbf{x}, \alpha^*)$ which may differ from $p(\mathbf{x}, \alpha_0)$ only on a set of zero measure.
- Demonstration:
 - Jensen's inequality implies:

$$\int \ln \frac{p(\mathbf{x}, \alpha)}{p(\mathbf{x}, \alpha_0)} dF(\mathbf{x}) \leq \int \ln \frac{p(\mathbf{x}, \alpha)}{p(\mathbf{x}, \alpha_0)} p(\mathbf{x}, \alpha_0) d\mathbf{x} = \ln 1 = 0$$

- So, the first assertion is proved by:

$$\int \ln \frac{p(\mathbf{x}, \alpha)}{p(\mathbf{x}, \alpha_0)} dF(\mathbf{x}) = \int \ln p(\mathbf{x}, \alpha) dF(\mathbf{x}) - \int \ln p(\mathbf{x}, \alpha_0) dF(\mathbf{x}) \leq 0$$

Assertions (II)

The Bregtanolle-Huber inequality

- The Bregtanolle-Huber inequality:

$$\int |p(\mathbf{x}, \alpha) - p(\mathbf{x}, \alpha_0)| d(\mathbf{x}) \leq 2\sqrt{1 - \exp\{R(\alpha_0) - R(\alpha)\}}$$

is valid.

Conclusion

- The functions $p(\mathbf{x}, \alpha^*)$ which are ε -close to the minimum:

$$R(\alpha^*) - \inf_{\alpha \in \Lambda} R(\alpha) < \varepsilon$$

will be $2\sqrt{1 - \exp\{-\varepsilon\}}$ -close to the required density in the L_1 metric.

Restrictions

- The density estimation problem in the Fisher-Wald setting is that the set of functions $Q(\mathbf{z}, \alpha)$ is subject to the following restrictions:
 - The vector \mathbf{z} coincides with the vector \mathbf{x} .
 - The set of functions $Q(\mathbf{z}, \alpha)$, $\alpha \in \Lambda$, is on the form

$$Q(\mathbf{z}, \alpha) = -\ln p(\mathbf{x}, \alpha)$$

where $p(\mathbf{x}, \alpha)$ is a set of density functions.

- The loss function takes on arbitrary values on the interval $(-\infty, \infty)$.

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Introduction

- We have seen that the pattern recognition, the regression and the density estimation problems can be reduced to this scheme by specifying a loss function in the risk functional.
- Now, how can we minimize the risk functional when the density function is unknown?
 - Classical: empirical risk minimization (ERM).
 - New one: structural risk minimization (SRM).

Empirical Risk Minimization

Definition

- Instead of minimizing the risk functional:

$$R(\alpha) = \int Q(\mathbf{z}, \alpha) dF(\mathbf{z}), \quad \alpha \in \Lambda$$

minimize the empirical risk functional

$$R_{emp}(\alpha) = \frac{1}{l} \sum_{i=1}^l Q(\mathbf{z}_i, \alpha), \quad \alpha \in \Lambda$$

on the basis of empirical data $\mathbf{z}_1, \dots, \mathbf{z}_l$ obtained according to a distribution function $F(\mathbf{z})$.

Empirical Risk Minimization

Considerations

- The functional is explicitly defined and it is subject to minimization.
- The problem is to establish conditions under which the minimum of the empirical risk functional, $Q(\mathbf{z}, \alpha_f)$, is closed to the desired one $Q(\mathbf{z}, \alpha_0)$.

Empirical Risk Minimization

Pattern recognition problem (I)

- The pattern recognition problem is considered as the minimization of the functional

$$R(\alpha) = \int L(\omega, \phi(\mathbf{x}, \alpha)) dF(\omega, \mathbf{x}), \quad \alpha \in \Lambda$$

on a set of functions $\phi(\mathbf{x}, \alpha)$, $\alpha \in \Lambda$, that take on only a finite number of values, on the basis of empirical data $(\mathbf{x}_1, \omega_1), \dots, (\mathbf{x}_l, \omega_l)$.

Empirical Risk Minimization

Pattern recognition problem (II)

- Considering the empirical risk functional

$$R_{emp}(\alpha) = \frac{1}{l} \sum_{i=1}^l L(\omega_i, \phi(\mathbf{x}_i, \alpha)), \quad \alpha \in \Lambda$$

- When $L(\omega_i, \alpha) \in \{0, 1\}$ (0 if $\omega = \phi$ and 01 if $\omega \neq \phi$), minimization of the empirical risk functional is equivalent to minimizing the number of training errors.

Empirical Risk Minimization

Regression problem (I)

- The regression problem is considered as the minimization of the functional

$$R(\alpha) = \int (y - f(\mathbf{x}, \alpha))^2 dF(y, \mathbf{x}), \quad \alpha \in \Lambda$$

on a set of functions $f(\mathbf{x}, \alpha)$, $\alpha \in \Lambda$, on the basis of empirical data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_l, y_l)$.

Empirical Risk Minimization

Regression problem (II)

- Considering the empirical risk functional

$$R_{emp}(\alpha) = \frac{1}{l} \sum_{i=1}^l (y_i - f(\mathbf{x}_i, \alpha))^2, \quad \alpha \in \Lambda$$

- The method of minimizing the empirical risk functional is known as the *Least-Squares method*.

Empirical Risk Minimization

Density estimation problem (I)

- The density estimation problem is considered as the minimization of the functional

$$R(\alpha) = \int \ln p(\mathbf{x}, \alpha) dF(\mathbf{x}), \quad \alpha \in \Lambda$$

on a set of densities $p(\mathbf{x}, \alpha)$, $\alpha \in \Lambda$, using i.i.d. empirical data $\mathbf{x}_1, \dots, \mathbf{x}_l$.

Empirical Risk Minimization

Density estimation problem (II)

- Considering the empirical risk functional

$$R_{emp}(\alpha) = - \sum_{i=1}^l \ln p(\mathbf{x}_i, \alpha), \quad \alpha \in \Lambda$$

it is the same solution which comes from the *Maximum Likelihood* method (in the Maximum Likelihood method a plus sign is used in front of the sum instead of the minus sign).

For Further Reading



The Nature of Statistical Learning Theory. Vladimir N. Vapnik. ISBN: 0-387-98780-0. 1995.



Statistical Learning Theory. Vladimir N. Vapnik. ISBN: 0-471-03003-1. 1998.

Questions?

Thank you very much for your attention.

- Contact:
 - Miguel Angel Veganzones
 - Grupo Inteligencia Computacional
 - Universidad del País Vasco - UPV/EHU (Spain)
 - E-mail: miguelangel.veganzones@ehu.es
 - Web page: <http://www.ehu.es/computationalintelligence>