# Splitting methods for the time integration of wave equations 

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We are concerned with the application of splitting methods for the time-integration of wave equations, for instance

## The semilinear wave equations

 in a bounded $\Omega \subset \mathbb{R}^{d}$ with homogeneous Dirichlet boundary conds.$$
\begin{aligned}
u_{t t} & =\Delta u+f(u) & & \text { in } \Omega \times \mathbb{R}, \\
u & =0 & & \text { in } \partial \Omega \times \mathbb{R}, \\
u(0) & =u_{0}, \quad u_{t}(0)=v_{0} & & \text { in } \Omega .
\end{aligned}
$$

We also consider
The semilinear wave equation with periodic boundary conditions

$$
\begin{aligned}
& u_{t t}=\Delta u+f(u) \\
& u(0)=u_{0}, \quad u_{t}(0)=v_{0} \quad \text { in } \quad \mathbb{T}^{d} \times \mathbb{R}, \\
& \mathbb{T}^{d} .
\end{aligned}
$$

## Splitting methods

The simplest splitting method consists on approximating $e^{t L}$ by splitting the operator $L$ as $X+Y$ and

$$
e^{t(X+Y)}=\left(e^{\tau(X+Y)}\right)^{m} \approx\left(e^{\tau X} e^{\tau Y}\right)^{m}
$$

with a small time-step $\tau=t / m$. Alternatively, one can use the

## Strang splitting

$$
e^{\tau(X+Y)} \approx e^{\frac{\tau}{2} X} e^{\tau Y} e^{\frac{\tau}{2} X} .
$$

Using more general products of exponentials is also possible:

$$
e^{\tau(X+Y)} \approx e^{\tau a_{1} X} e^{\tau b_{1} Y} \cdots e^{\tau a_{m} X} e^{\tau b_{m} Y}
$$

with appropriately chosen $a_{1}, b_{1}, \cdots, a_{m}, b_{m} \in \mathbb{R}$.

How to split the semilinear wave equation?

- A possible option is splitting the wave equation as

$$
u_{t t}=\Delta u, \quad \text { and } \quad u_{t t}=f(u)
$$

- A better option, provided that $f(u)=\rho u+\mathcal{O}\left(u^{2}\right)$, is

$$
u_{t t}=\Delta u+\rho u, \quad \text { and } \quad u_{t t}=f(u)-\rho u
$$

- A third option, based on rewritting the equations as

$$
u_{t}=v, \quad v_{t}=\Delta u+f(u)
$$

and splitting it as

$$
\left\{\begin{array} { l } 
{ u _ { t } = v , } \\
{ v _ { t } = 0 , }
\end{array} \quad \text { and } \quad \left\{\begin{array}{l}
u_{t}=0 \\
v_{t}=\Delta u+f(u)
\end{array}\right.\right.
$$

But that only makes sense after spatial semidiscretization!

## Semidiscretization in space

For a spatial grid $x_{1}, \ldots, x_{N} \in \Omega$, consider

$$
q(t) \approx\left(\begin{array}{c}
u\left(x_{1}, t\right) \\
\vdots \\
u\left(x_{N}, t\right)
\end{array}\right), \quad p(t) \approx\left(\begin{array}{c}
u_{t}\left(x_{1}, t\right) \\
\vdots \\
u_{t}\left(x_{N}, t\right)
\end{array}\right)
$$

determined as the solutions of a

## Semidiscretized problem

$$
\frac{d}{d t} q=p, \quad \frac{d}{d t} p=A q+g(q),
$$

with initial values $q(0)=q_{0}, \quad p(0)=q_{0}$.
Here, $A \in \mathbb{R}^{N \times N}$ is such that

$$
A q(t) \approx\left(\begin{array}{c}
\Delta u\left(x_{1}, t\right) \\
\vdots \\
\Delta u\left(x_{N}, t\right)
\end{array}\right), \quad \text { and } \quad g(q(t))=\left(\begin{array}{c}
f\left(u\left(x_{1}, t\right)\right) \\
\vdots \\
f\left(u\left(x_{N}, t\right)\right)
\end{array}\right) .
$$

Application of $e^{\tau(A+B)}=e^{\tau / 2 A} e^{\tau B} e^{\tau / 2 A}$ to the equations split as

$$
\left\{\begin{array} { l } 
{ \frac { d } { d t } q = p , } \\
{ \frac { d } { d t } p = 0 , }
\end{array} \quad \text { and } \quad \left\{\begin{array}{l}
\frac{d}{d t} q=0 \\
\frac{d}{d t} p=A q+g(q)
\end{array}\right.\right.
$$

gives the

## Leapfrog method

$\left(q_{n}, p_{n}\right) \approx\left(q\left(t_{n}\right), p\left(t_{n}\right)\right)$ computed for $t_{n}=n \tau$ as follows:

$$
\begin{aligned}
p_{n-\frac{1}{2}} & =p_{n-1}+\frac{\tau}{2}\left(A q_{n-1}+g\left(q_{n-1}\right)\right) \\
q_{n} & =q_{n-1}+\tau p_{n-\frac{1}{2}} \\
p_{n} & =p_{n-\frac{1}{2}}+\frac{\tau}{2}\left(A q_{n}+g\left(q_{n}\right)\right),
\end{aligned}
$$

or in two step formulation, $q_{1}=q_{0}+\tau p_{0}+\frac{\tau^{2}}{2}\left(A q_{0}+g\left(q_{0}\right)\right)$ and

$$
q_{n+1}-2 q_{n}+q_{n-1}=\tau^{2}\left(A q_{n}+g\left(q_{n}\right)\right)
$$

Central finite differences in space and leapfrog in time
Example: 1D-wave equation with homogeneous Dirichlet b.c.
$\Omega=(0,1), f(u)=2 u-4 u^{3}, u_{0}(x)=\frac{1}{10+\sin ^{2}(\pi x)}, v_{0}(x)=0$,
$x_{j}=j h,(j=1, \ldots, 15), h=\frac{1}{16}, \tau=\frac{h}{2}$.
Space discretization errors and time discr. errors versus time:


Standard ODE error analysis: Consider a semidiscretized problem (for a fixed small $h$ ) and study errors as $\tau \rightarrow 0$.

We would like to analyze the full discretization error as $h, \tau \rightarrow 0$.

## Approx. analysis of fully discretized solutions of small amplitude

Assume that

- $f(0)=0$, so that for $u$ with small amplitude, $f(u) \approx f^{\prime}(0) u$,
- $-\left(A+f^{\prime}(0) I\right)$ is diagonalizable with positive real eigenvalues. Then consider $B=\left(-\left(A+f^{\prime}(0) I\right)\right)^{1 / 2}$, and analyze leapfrog method applied to

$$
\frac{d}{d t} q=p, \quad \frac{d}{d t} p=-B^{2} q
$$

If $\tau \leq \frac{2}{\rho(B)}$, then the numerical solution given by

$$
q_{n+1}-2 q_{n}+q_{n-1}=-\tau^{2} B^{2} q_{n}
$$

(where $q_{1}=q_{0}+\tau p_{0}-\frac{\tau^{2}}{2} B^{2} q_{0}$ ) lies in the trajectory of the

## Modified problem

$$
\frac{d}{d t} \tilde{q}=\tilde{p}, \quad \frac{d}{d t} \tilde{p}=-\tilde{B}^{2} q,
$$

with

$$
\tilde{B}=\frac{2}{\tau} \arcsin \left(\frac{\tau}{2} B\right)=B+\frac{\tau^{2}}{24} B^{3}+\cdots
$$

and initial values

$$
\tilde{q}(0)=q_{0}, \quad \tilde{p}(0)=\left(I-\frac{\tau^{2}}{4} B^{2}\right)^{-\frac{1}{2}} p_{0}=p_{0}-\frac{\tau^{2}}{8} B^{2} p_{0}+\cdots .
$$

Central finite differences in space and leapfrog in time
Example: 1D-wave equation with homogeneous Dirichlet b.c.
Previous example with $h=\frac{1}{16}$ and $\tau=h$ (instead of $\tau=\frac{h}{2}$ ). Space, time and full discretization errors versus time:


## 2nd order central finite differences with leapfrog in 1D

Stability requirement:

$$
|\tau| \leq \frac{2}{\rho(B)}=\frac{h}{\sin \left(\frac{(1-h) \pi}{2}\right)}, \quad(\text { for } f(u)=0,)
$$

hence, leapfrog scheme is stable for $\tau=h$.
Exceptional performance of full discretization for $\tau=h$ :

- $\omega_{k}=k \pi \rightarrow \omega_{k}^{h}=\frac{2}{h} \sin (k \pi h / 2) \rightarrow \omega_{k}^{h, \tau}=\frac{2}{\tau} \arcsin \left(\tau \omega_{k}^{h} / 2\right)$. If $\tau=h$, then $\omega_{k}^{h, \tau}=k \pi$ !
- Solutions of $u_{t t}=u_{x x}$ exactly satisfy


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- Solutions of $u_{t t}=u_{x x}$ exactly satisfy

$$
\begin{aligned}
& \frac{1}{\tau^{2}}(u(x, t+\tau)-2 u(x, t)+u(x, t-\tau))= \\
& \frac{1}{h^{2}}(u(x+h, t)-2 u(x, t)+u(x-h, t))
\end{aligned}
$$

for $\tau=h$.

Fourier spectral collocation methods with leapfrog in time:
Example: 1D-wave equation with periodic boundary conditions
$x \in(0,2 \pi), f(u)=\frac{u}{10}-4 u^{3}, u_{0}(x)=\frac{e^{\sin (x)}}{10}, v_{0}(x)=0$, $h=\frac{2 \pi}{16}, \tau=\frac{h}{4}<\frac{2}{\rho(B)} \approx \frac{2 h}{\pi}$. Variation of discrete Hamiltonian, momentum and oscillatory energy:


Fourier spectral collocation methods with leapfrog in time: Space discr. errors and time discr. errors (for $\tau=h / 4$ and $\tau=h / 24$ ) versus time:


Fourier spectral collocation methods with optimized splitting:

$$
e^{\tau(X+Y)} \approx e^{\tau a_{1} X} e^{\tau b_{1} Y} \cdots e^{\tau a_{m} X} e^{\tau b_{m} Y}
$$

Time discr. error of new splitting method with $m=17$ and $\tau=\frac{m h}{4}$


Fourier spectral collocation methods with optimized splitting methods for non-smooth data: $f(u)=2 u^{3}, n=64$,

$$
u_{0}(x)=\left\{\begin{array}{cl}
\frac{x}{20 \pi} & \text { if } 0 \leq x \leq \pi \\
\frac{2 \pi-x}{20 \pi} & \text { if } \pi \leq x \leq 2 \pi .
\end{array}, \quad v_{0}(x)=0\right.
$$

(i) Space discr. errors, (ii) time discr. errors for leapfrog with $\tau=h / 2$ and (iii) another new method with $m=17$ and $\tau=\frac{m h}{2}$.

Errors


Consider the problem

$$
\frac{d}{d t} q=p, \quad \frac{d}{d t} p=A q+g(q)
$$

arising from the spatial semidiscretization of a wave equation.

## Splitting scheme

$\left(q_{n}, p_{n}\right) \approx\left(q\left(t_{n}\right), p\left(t_{n}\right)\right)$ computed for $t_{n}=n \tau$ as follows: Take $Q_{0}=q_{n-1}, P_{0}=p_{n-1}$, and compute for $j=1, \ldots, m$

$$
\begin{aligned}
P_{j} & =P_{j-1}+a_{j} \tau\left(A Q_{j-1}+g\left(q_{j-1}\right)\right) \\
Q_{j} & =Q_{j}+b_{j} \tau P_{j}
\end{aligned}
$$

and take $\left(q_{n}, p_{n}\right)=\left(Q_{m}, P_{m}\right)$.
The coefficients $a_{j}$ and $b_{j}(j=1, \ldots, m)$ appropriately chosen real numbers.

We want to analyse the application of the splitting method to

$$
\frac{d}{d t} q=p, \quad \frac{d}{d t} p=-B^{2} q,
$$

where $B^{2}=-\left(f^{\prime}(0) I+A\right)$. We assume that $B$ is symmetric positive definite.

- Obviously, $\rho(B) \rightarrow \infty$ as the spacial discretization converges to the continuous problem.
- For each splitting method, there exists $x^{*} \geq 0$ such that the scheme is stable if $\tau<\frac{x^{*}}{\rho(B)}\left(x^{*}=2\right.$ for leapfrog).
- We want to apply a splitting method with $\tau=\frac{r}{\rho(B)}$ for fixed $r \leq x^{*}$. How are the time discretization errors as $\rho(B) \rightarrow \infty$ ?
It depends on the splitting method, and the (smoothness of the) initial data $u_{0}, v_{0}$.

We obtain estimates depending on

$$
\begin{aligned}
C_{s} & :=\left\|B^{s+1} q_{0}\right\|+\left\|B^{s} p_{0}\right\| \\
& \approx\left\|\left(f^{\prime}(0)+\Delta\right)^{\frac{s+1}{2}} u_{0}\right\|+\left\|\left(f^{\prime}(0)+\Delta\right)^{\frac{s}{2}} v_{0}\right\| .
\end{aligned}
$$

## Theorem

Given a splitting scheme with stability threshold $x^{*}$, for each $s>0$ and each $r \in\left(0, x^{*}\right)$, there exist $\mu_{s}(r), \nu_{s}(r)>0$ such that

$$
\left\|q_{n}-q\left(t_{n}\right)\right\| \leq \frac{C_{s}}{\rho(B)^{s}}\left(\left|t_{n}\right| \mu_{s}(r)+\nu_{s}(r)\right)
$$

for $t_{n}=n \tau$ with $\tau=r / \rho(B)$.

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$$

$$
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Similar estimates can be obtained for $\left\|p_{n}-p\left(t_{n}\right)\right\|$.

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$$

$$
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$$

Similar estimates can be obtained for $\left\|p_{n}-p\left(t_{n}\right)\right\|$.
For the leapfrog method, given $0 \leq s \leq 2$ and $r<x^{*}=2$,

$$
\begin{aligned}
\mu_{s}(r) & =\sup _{0<x \leq r}\left|\left(\frac{r}{x}\right)^{s}\left(\frac{2}{x} \arcsin \left(\frac{x}{2}\right)-1\right)\right|, \\
\nu_{s}(r) & =\sup _{0<x \leq r}\left|\left(\frac{r}{x}\right)^{s} \sqrt{1-\frac{x^{2}}{4}}\right| .
\end{aligned}
$$

Given a splitting scheme with coefficients $a_{1}, b_{1}, \ldots, a_{m}, b_{m}$, there exist $x^{*} \geq 0$ and two even functions $\kappa(x)$ and $\gamma(x)$ such that, if $B$ is symmetric positive definite and $|\tau| \rho(B) \leq x^{*}$, then

$$
q_{n}=\tilde{q}(n \tau), \quad p_{n}=\gamma(\tau B) \tilde{p}(n \tau)
$$

where $(\tilde{q}(t), \tilde{p}(t))$ is the exact solution of

$$
\frac{d}{d t} \tilde{q}=\tilde{p}, \quad \frac{d}{d t} \tilde{p}=-\tilde{B}^{2} q
$$

with $\tilde{B}=\kappa(\tau B) B$ and initial values

$$
\tilde{q}(0)=q_{0}, \quad \tilde{p}(0)=\gamma(\tau B)^{-1} p_{0} .
$$

Furthermore, the theorem above holds with

$$
\begin{aligned}
\mu_{s}(r) & =\sup _{0<x \leq r}\left|\left(\frac{r}{x}\right)^{s}(\kappa(x)-1)\right| \\
\nu_{s}(r) & =\sup _{0<x \leq r}\left|\left(\frac{r}{x}\right)^{s}(\gamma(x)-1)\right|
\end{aligned}
$$

- Construction of optimized splitting methods with relatively large number $m$ of factors with optimized values of $\mu_{s}(r)+\epsilon \nu_{s}(r)$ for prescribed $m, s, r, \epsilon$.
- Testing/analysis of methods for (weakly) non-linear wave equations, and eventually adapt the optimization criteria (Conjecture: Small coefficients $\left|a_{j}\right|,\left|b_{j}\right|$ required, in addition to small $\left.\mu_{s}(r)+\epsilon \nu_{s}(r)\right)$.
- Apply and adapt optimized splitting methods to other linear problems of the form

$$
\frac{d}{d t} q=M p, \quad \frac{d}{d t} p=-N q
$$

with all eigenvalues in the imaginary axis: Schrödinger, Maxwel.

- . .

Parameters for known splitting methods with $m$ stages and order $2 n$

- Relative stability threshold $x^{*} / m$,
- Values for $\left(\mu_{s}(r m), \nu_{s}(r m)\right)$ in the error estimate

$$
\left\|q_{n}-q\left(t_{n}\right)\right\| \leq \frac{C_{s}}{\rho(B)^{s}}\left(\left|t_{n}\right| \mu_{s}(r m)+\nu_{s}(r m)\right)
$$

with time-step $\tau=\frac{r m}{\rho(B)}$.

| Method | Leapfrog | Yoshida | Blanes \& Moan |
| :---: | :---: | :---: | :---: |
| $m$ | 1 | 4 | 6 |
| $2 n$ | 2 | 4 | 4 |
| $x^{*} / m$ | 2 | 0.393 | 0.482 |
| $\left(\mu_{2}\left(\frac{5 m}{4}\right), \nu_{2}\left(\frac{5 m}{4}\right)\right)$ | $(0.078,0.27)$ | $(\infty, \infty)$ | $(\infty, \infty)$ |
| $\left(\mu_{2}(m), \nu_{2}(m)\right)$ | $(0.0472,0.155)$ | $(\infty, \infty)$ | $(\infty, \infty)$ |
| $\left(\mu_{2}\left(\frac{3 m}{10}\right), \nu_{2}\left(\frac{3 m}{10}\right)\right)$ | $(0.0037,0.011)$ | $(0.186,0.230)$ | $(0.0002,0.003)$ |
| $\left(\mu_{4}\left(\frac{3 m}{10}\right), \nu_{4}\left(\frac{3 m}{10}\right)\right)$ | $(\infty, \infty)$ | $(0.186,0.230)$ | $(0.0002,0.003)$ |

