

Formal averaging of periodic and quasi-periodic vector fields

Ander Murua

Work in progress with P. Chartier and J.M. Sanz-Serna

Euskal Herriko Unibertsitatea

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Example (Fermi-Pasta-Ulam problem)

Hamiltonian system with Hamiltonian function

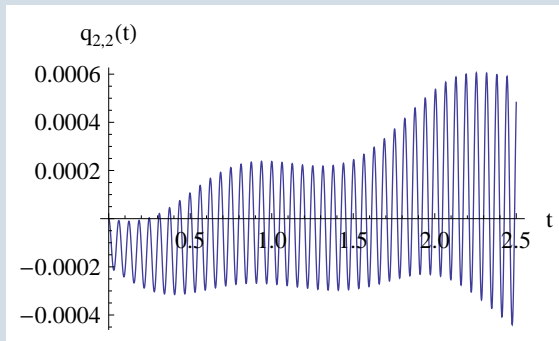
$$\begin{aligned}H(p, \bar{p}, q, \bar{q}) &= \frac{1}{2}(p^T p + \bar{p}^T \bar{p}) + \frac{1}{2\epsilon^2} q^T q + U(q, \bar{q}), \\U(q, \bar{q}) &= \frac{1}{4} ((\bar{q}_1 - q_1)^4 + (\bar{q}_m + q_m)^4) \\&\quad + \frac{1}{4} \sum_{j=1}^{m-1} (\bar{q}_{j+1} - q_{j+1} - \bar{q}_j - q_j)^4.\end{aligned}$$

We consider $m = 3$, $\epsilon = 1/100$, and initial values

$$\bar{p}(0) = p(0) = \bar{q}(0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad q(0) = \begin{pmatrix} \epsilon \\ 0 \\ 0 \end{pmatrix}.$$

Example (Fermi-Pasta-Ulam problem (cont.))

Solution for the component $q_2(t)$,

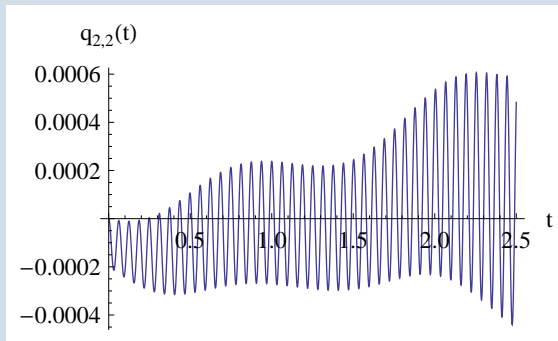


and for $n = 0, 1, 2, 3, \dots$,

$$q_2(2\pi\epsilon n)$$

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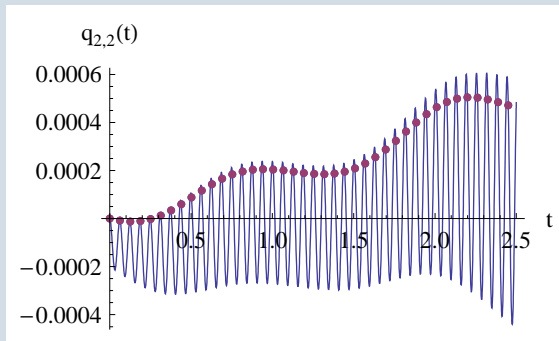


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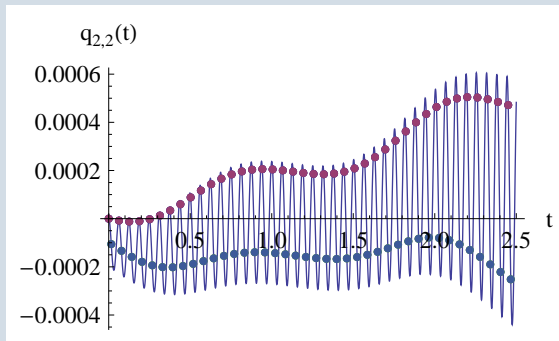


and for $n = 0, 1, 2, 3, \dots$,

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Example (Fermi-Pasta-Ulam problem (cont.))

Solution for the component $q_2(t)$,



and for $n = 0, 1, 2, 3, \dots$,

$$q_2(2\pi\epsilon n), \quad \text{and} \quad q_2\left(\frac{\pi\epsilon}{2} + 2\pi\epsilon n\right).$$

Consider a Hamiltonian system

$$\frac{d}{dt}y = J^{-1}\nabla H(y; \epsilon), \quad H(y; \epsilon) := \epsilon^{-1}H^0(y) + R(y),$$

Let $\varphi_\tau : \mathbb{R}^{2d} \rightarrow \mathbb{R}^{2d}$ be such that $\varphi_{t/\epsilon}$ is the t -flow of that system. Assume that the τ -flow φ_τ^0 of H^0 is (2π) -periodic. ($H^0(y)$ and $R(y)$ may depend on ϵ).

It can be shown that $\varphi_{2\pi}$ is a near-to-identity map,

Backward error analysis

There exists $\mathcal{H}(Y; \epsilon) = \mathcal{H}_0(Y) + \epsilon\mathcal{H}_1(Y) + \epsilon^2\mathcal{H}_2(Y) + \dots$,

$$\frac{d}{dt}Y = J^{-1}\nabla\mathcal{H}(Y; \epsilon),$$

such that, $Y(2\pi\epsilon n) = y(2\pi\epsilon n)$ if $Y(0) = y(0) = y_0$.

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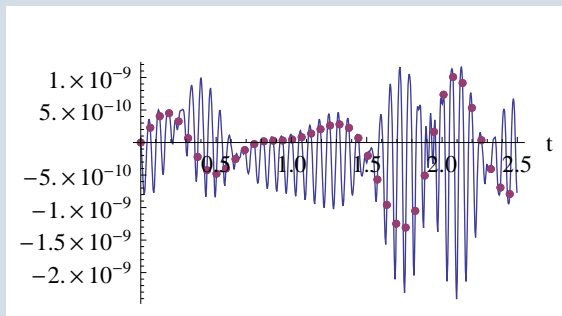
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Example (Fermi-Pasta-Ulam problem)

We consider

$$\begin{aligned}\tilde{\mathcal{H}}(Y, \epsilon) &:= \mathcal{H}_0(Y) + \epsilon^2 \mathcal{H}_2(Y) + \epsilon^4 \mathcal{H}_4(Y) \\ &= \mathcal{H}(Y; \epsilon) + \mathcal{O}(\epsilon^6),\end{aligned}$$

and plot the variation $\tilde{\mathcal{H}}(y(t); \epsilon) - \tilde{\mathcal{H}}(y(0); \epsilon)$



Smooth invariant

Under the previous assumptions for

$$\frac{d}{dt}y = J^{-1}\nabla H(y; \epsilon), \quad H(y; \epsilon) := \epsilon^{-1}H^0(y) + R(y),$$

consider $\mathcal{H}(Y; \epsilon) = \mathcal{H}_0(Y) + \epsilon\mathcal{H}_1(Y) + \epsilon^2\mathcal{H}_2(y) + \dots$ as before, then $\mathcal{H}(y; \epsilon)$ is a first integral of the original system.

Indeed, for $t_n = 2\pi\epsilon n$, $n = 1, 2, \dots$

$$H(Y(t_n); \epsilon) = H(y(t_n); \epsilon) = \text{Const}$$

and by a interpolating argument, $H(Y(t); \epsilon) = \text{Const}$, and thus

$$\{H, \mathcal{H}\} \equiv 0.$$

Numerical integration of HOS with ϵ -independent time-steps

Integrate the smooth system

$$\frac{d}{dt} Y = J^{-1} \nabla H(Y; \epsilon), \quad Y(0) = y_0$$

instead of the highly oscillatory one. Different options

- Symbolic-numeric algorithms using explicit knowledge of \mathcal{H}
- Purely numerical schemes that try to approximate $Y(t)$ by using H as input (HMSM, ...).

Motivated by that, we aim at

- Obtaining formulae for $\mathcal{H}(Y; \epsilon)$ and its solutions $Y(t)$
- Such formulae should be as explicit as possible and
- Of universal character

Time-dependent ($2\pi\epsilon$)-periodic change of variables

Let φ_τ^0 be the τ -flow of H^0 , consider

$$y = \varphi_{t/\epsilon}^0(\hat{y}).$$

Notice that for $t_n = 2\pi\epsilon n$, it reduces to the identity map.

The system with $H(y; \epsilon) = \epsilon^{-1}H^0(y) + R(y)$ is transformed into a non-autonomous Hamiltonian system with $\hat{H}(\hat{y}, t/\epsilon)$, where

$$\hat{H}(\hat{y}, \tau) := R(\varphi_\tau^0(\hat{y})) = \sum_{k \in \mathbb{Z}} e^{ik\tau} \hat{H}_k(\hat{y}).$$

$(\varphi_\tau^0(\hat{y}))$ is (2π) -periodic in τ . Clearly,

$$\frac{d}{dt} \hat{y} = \sum_{k \in \mathbb{Z}} e^{ikt/\epsilon} f_k(\hat{y}).$$

From now on, we consider systems of that general form. The $f_k(\hat{y})$ may depend on ϵ , but not reflected in the notation.

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Standard high order averaging [Sanders, Verhulst, Murdock 2007]

Under suitable assumptions on the HOS

$$\frac{d}{dt}y = \sum_{k \in \mathbb{Z}} e^{ikt/\epsilon} f_k(y).$$

there exists a formal $(2\pi\epsilon)$ -periodic change of variables $y = K(Y, t/\epsilon)$ that transforms the original HOS into the (*averaged*) autonomous equations

$$\frac{d}{dt}Y = F(Y; \epsilon) := F_0(Y) + \epsilon F_1(Y) + \epsilon^2 F_2(Y) + \dots$$

The change of variables $y = K(Y, \tau)$ is not unique:

- **Stroboscopic averaging:** $K(Y, 0) = Y$, which implies $Y(2\pi\epsilon n) = y(2\pi\epsilon n)$ for all $n \in \mathbb{Z}$.
- $\int_0^{2\pi} K(Y, \tau) d\tau = Y$,

Stroboscopic averaging of HOS autonomous Hamiltonian systems

Back to the HOS Hamiltonian system $H(y) = \epsilon^{-1}H^0(y) + R(y)$, the $(2\pi\epsilon)$ -periodic change of variables

$$y = \varphi_{t/\epsilon}^0(K(Y, t/\epsilon))$$

transforms the original **HOS autonomous** Hamiltonian H into a **smooth autonomous** Hamiltonian \mathcal{H} .

Comments:

- The smooth Hamiltonian \mathcal{H} is exactly the same as that derived from backward error analysis applied to $\varphi_{2\pi\epsilon}$.
- The (stroboscopically) averaged system of general HOS

$$\frac{d}{dt}y = \sum_{k \in \mathbb{Z}} e^{ikt/\epsilon} f_k(y).$$

can also be derived from backward error analysis applied to the near-identity map ψ such that $\psi(y(0)) = y(2\pi\epsilon)$ for any solution $y(t)$.

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We next focus on obtaining, using standard techniques in numerical analysis (B-series, ...), universal formulae for the averaging of non-autonomous periodic HOS.

B-series expansion of solution of the HOS

For the solutions of $\dot{y} = \sum_k e^{ikt/\epsilon} f_k(y)$,

$$y(t) = y(0) + \sum_{u \in \mathcal{T}} \frac{\alpha_u(t)}{\sigma_u} \mathcal{F}_u(y(0)),$$

\mathcal{T} is the set of rooted trees labelled by $k \in \mathbb{Z}$, and for each $u \in \mathcal{T}$,

- the coefficients $\alpha_u(\tau)$ are linear combinations of $t^j e^{ikt/\epsilon}$,
- The elementary differentials $\mathcal{F}_u : \mathbb{R}^d \rightarrow \mathbb{R}^d$ are smooth, ($\sigma_u \in \mathbb{Z}$ is a normalization factor.)

Elementary coefficients

$$\alpha_u(t) = \int_0^t e^{ikt'/\epsilon} \alpha_{u_1}(t') \cdots \alpha_{u_m}(t') dt', \quad u = [u_1 \cdots u_m]_k.$$

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
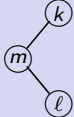
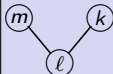
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Examples for rooted trees with less than 4 vertices



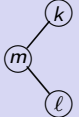
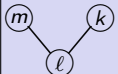
u	$\mathcal{F}_u(y)$	$\alpha_u(t)$
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	$f'_m(y)f_k(y)$	$\int_0^t \int_0^{t_2} e^{\frac{i(kt_1+mt_2)}{\epsilon}} dt_1 dt_2$
	$f'_l(y)f'_m(y)f_k(y)$	$\int_0^t \int_0^{t_3} \int_0^{t_2} e^{\frac{i(kt_1+mt_2+\ell t_3)}{\epsilon}} dt_1 dt_2 dt_3$
	$f''_l(y)(f_m(y), f_k(y))$	$\int_0^t \int_0^{t_2} e^{\frac{i(kt_1+mt_1+\ell t_2)}{\epsilon}} dt_1 dt_2$

For each $u \in \mathcal{T}$, $\alpha_u(t) = \alpha_u(t, t/\epsilon)$, with

$$\alpha_u(t, \tau) = \sum_{k \in \mathbb{Z}} \alpha_u^k(t) e^{ik\tau},$$

where each $\alpha_u^k(t)$ is a polynomial in t .

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Relation with modulated Fourier series

For any solution of $\dot{y} = \sum_k e^{ikt/\epsilon} f_k(y)$,

$$\begin{aligned}y(t) &= y(0) + \sum_{u \in \mathcal{I}} \frac{\alpha_u(t, t/\epsilon)}{\sigma_u} \mathcal{F}_u(y(0)), \\&= y(0) + \sum_{u \in \mathcal{I}} \sum_{k \in \mathbb{Z}} \frac{\alpha_u^k(t)}{\sigma_u} e^{ikt/\epsilon} \mathcal{F}_u(y(0)), \\&= y(0) + \sum_{k \in \mathbb{Z}} \left(\sum_{u \in \mathcal{I}} \frac{\alpha_u^k(t)}{\sigma_u} \mathcal{F}_u(y(0)) \right) e^{ikt/\epsilon} \\&= y^0(t) + \sum_{k \in \mathbb{Z} \setminus \{0\}} e^{ikt/\epsilon} z^k(t).\end{aligned}$$

Modulated Fourier series versus B-series approach

In the case of exact solution of the Hamiltonian system with $H(y; \epsilon) = \epsilon^{-1}H^0(y) + R(y)$:

- Modulated Fourier approach [Hairer& Lubich 2000]: Expand exact solution $y(t)$ in the form

$$y(t) = y^0(t) + \sum_{k \in \mathbb{Z} \setminus \{0\}} e^{ikt/\epsilon} z^k(t)$$

by Taylor-expanding $R(y)$ around $y^0(t)$.

- Our approach: Expand $\hat{y}(t) = \varphi_{-t/\epsilon}(y(t))$ as a B-series in terms of the Fourier modes \hat{H}_k of

$$\hat{H}(\hat{y}, \tau) := R(\varphi_{\tau}^0(\hat{y})) = \sum_{k \in \mathbb{Z}} e^{ikt/\epsilon} \hat{H}_k(\hat{y}).$$

Averaging with B-series

There exist $\bar{\beta}_u, \bar{\alpha}_u(t), \kappa_u(\tau)$, $u \in \mathcal{T}$, ($\bar{\alpha}_u(t)$ polynomial, $\kappa_u(\tau)$ (2π) -periodic) such that for any solution $y(t)$ of the HOS

$$y(t) = K(Y(t), t/\epsilon), \quad \frac{d}{dt} Y(t) = F(y(t)),$$

where

$$F(Y) = \sum_{u \in \mathcal{T}} \frac{\bar{\beta}_u}{\sigma_u} \mathcal{F}_u(Y),$$

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$$K(Y, \tau) = Y + \sum_{u \in \mathcal{T}} \frac{\kappa_u(\tau)}{\sigma_u} \mathcal{F}_u(Y),$$

Not unique (but uniquely determined for prescribed $\kappa_u(0)$, $u \in \mathcal{T}$).

That is, $\alpha(t, \tau) = \bar{\alpha}(t)\kappa(\tau)$ with $\frac{d}{dt}\bar{\alpha}(t) = \bar{\alpha}(t)\bar{\beta}$.

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Stroboscopic averaging: $K(Y, 0) = Y$

So that $Y(2\pi n\epsilon) = y(2\pi n\epsilon)$. Thus, $\kappa(0) = \mathbb{1}$ which implies $\bar{\alpha}(0) = \mathbb{1}$, and

$$\bar{\alpha}_u(t) = \alpha_u(t, 0), \quad \kappa_u(\tau) = \alpha_u(0, \tau), \quad \bar{\beta}_u = \left. \frac{d}{dt}\bar{\alpha}_u(t) \right|_{t=0}.$$

'Classical' averaging: $\frac{1}{2\pi} \int_0^{2\pi} K(Y, \tau) d\tau = Y$

$Y(2\pi n\epsilon) \neq y(2\pi n\epsilon)$. We have $\frac{1}{2\pi} \int_0^{2\pi} \kappa(\tau) d\tau = \mathbb{1}$, and thus

$$\bar{\alpha}_u(t) = 1/(2\pi) \int_0^{2\pi} \alpha_u(t, \tau) d\tau, \quad \kappa_u(\tau) = (\bar{\alpha}(0)^{-1} \alpha(0, \tau))_u,$$
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Given $\omega \in \mathbb{R}^d$ non-resonant and $\theta(t) = \theta_0 + \omega t$,

$$\frac{d}{dt}y := f(y, \theta(t)) = \sum_{k \in \mathbb{Z}^d} e^{i(k \cdot \theta(t))} f_k(y), \quad , \quad y(0) = y_0,$$

Expansion of solutions of quasi-periodic vector fields

$$y(t) = y_0 + \sum_{w \in \mathcal{W}} \alpha_w(t, \theta(t)) f_w(y_0),$$

where \mathcal{W} is the set of 'words' $w = k_1 \cdots k_r$ on the alphabet \mathbb{Z}^d ,

$$\alpha_{k_1 \cdots k_r}(t) = \int_0^t \int_0^{t_r} \cdots \int_0^{t_2} e^{i\omega \cdot (k_1 t_1 + \cdots + k_r t_r)} dt_1 \cdots dt_r,$$

$$f_{k_1 \cdots k_r}(y) = \frac{\partial}{\partial y} f_{k_2 \cdots k_r}(y) f_{k_1}(y),$$

In particular, $f_{mk} = f'_k f_m$, $f_{\ell mk} = f''_k(f_m, f_\ell) + f'_k f'_m f_\ell$.

Given $\omega \in \mathbb{R}^d$ non-resonant and $\theta(t) = \theta_0 + \omega t$,

$$\frac{d}{dt}y := f(y, \theta(t)) = \sum_{k \in \mathbb{Z}^d} e^{i(k \cdot \theta(t))} f_k(y), \quad , \quad y(0) = y_0,$$

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Indeed, consider for each $k \in \mathbb{Z}^d$, the Lie operator associated to f_k ,

$$E_k = \sum_{i=1}^{d'} f_k^i \frac{\partial}{\partial y^i}, \quad \text{so that} \quad f_{k_1 \dots k_r} = E_{k_1} \cdots E_{k_r}[\text{id}],$$

Let Φ_t be such that $\Phi_t[g](y_0) = g(y(t))$ for smooth $g(y)$

$$\begin{aligned} \frac{d}{dt} \Phi_t[g](y_0) &= \frac{d}{dt} g(y(t)) = \frac{\partial}{\partial y} g(y(t)) f(y(t), \theta(t)) \\ &= \sum_{k \in \mathbb{Z}^d} e^{ik \cdot \theta(t)} E_k[g](y(t)) = \sum_{k \in \mathbb{Z}^d} e^{ik \cdot \theta(t)} \Phi_t E_k[g](y_0). \end{aligned}$$

Linear non-autonomous quasi-periodic differential equation

$$\frac{d}{dt} \Phi_t = \Phi_t \sum_{k \in \mathbb{Z}^d} e^{ik \cdot \theta(t)} E_k, \quad \Phi_0 = I.$$

$$\Phi_t = I + \sum_{k_1 \dots k_r \in \mathcal{W}} \alpha_{k_1 \dots k_r}(t) E_{k_1} \cdots E_{k_r} \quad (\text{by Picard iteration})$$

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Recursive formulae for $\alpha_w(t, \theta)$

If $r \in \mathbb{Z}^+$, $k \in \mathbb{Z}^d - \{0\}$, $l \in \mathbb{Z}^d$, and $w \in \mathcal{W} \cup \{\emptyset\}$,

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Formal high order averaging: Find a factorization

$$I + \sum_{w \in \mathcal{W}} \alpha_w(t, \theta) E_w = \left(I + \sum_{w \in \mathcal{W}} \bar{\alpha}_w(t) E_w \right) \left(I + \sum_{w \in \mathcal{W}} \kappa_w(\theta) E_w \right)$$

$$\frac{d}{dt} \left(I + \sum_{w \in \mathcal{W}} \bar{\alpha}_w(t) E_w \right) = \left(I + \sum_{w \in \mathcal{W}} \bar{\alpha}_w(t) E_w \right) \left(\sum_{w \in \mathcal{W}} \bar{\beta}_w E_w \right).$$

Or more compactly,

$$\alpha(t, \theta) = \bar{\alpha}(t) \kappa(\theta), \quad \frac{d}{dt} \bar{\alpha}(t) = \bar{\alpha}(t) \bar{\beta}.$$

Pseudo-stroboscopic averaging: $\kappa(\theta_0) = \mathbb{1}$

$$\bar{\alpha}_w(t) = \alpha_w(t, \theta_0), \quad \kappa_w(\theta) = \alpha_w(0, \theta), \quad \bar{\beta}_w = \left. \frac{d}{dt} \bar{\alpha}_w(t) \right|_{t=0}.$$

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Pseudo-stroboscopic averaging for quasi-periodic problems

We get $y(t) = K(Y(t), \theta(t))$, ($\theta(t) = \theta_0 + \omega t$), where

$$\frac{d}{dt} Y = F(Y), \quad Y(0) = y_0,$$

with

$$K(Y, \theta) = Y + \sum_{w \in \mathcal{W}} \kappa_w(\theta) f_w(Y),$$

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Recursion for coefficients of averaged equation

$$\begin{aligned}\bar{\beta}_k &= 0, \quad \bar{\beta}_0 = 1, \quad \bar{\beta}_{0r+1} = 0, \\ \bar{\beta}_{0^r k} &= \frac{i}{k \cdot \omega} (\bar{\beta}_{0^{r-1} k} - \bar{\beta}_{0^r} e^{i(k \cdot \theta_0)}), \\ \bar{\beta}_{klw} &= \frac{i}{k \cdot \omega} (\bar{\beta}_{lw} - \bar{\beta}_{(k+l)w}), \\ \bar{\beta}_{0^r klw} &= \frac{i}{k \cdot \omega} (\bar{\beta}_{0^{r-1} klw} - \bar{\beta}_{0^r (k+l)w}),\end{aligned}$$

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Similar recursions for $\bar{\alpha}(t)$ and $\kappa(\theta)$ from those of $\alpha(t, \theta)$.

But does the factorization

$$\alpha(t, \theta) = \bar{\alpha}(t)\kappa(\theta), \quad \frac{d}{dt}\bar{\alpha}(t) = \bar{\alpha}(t)\bar{\beta}, \quad \kappa(\theta_0) = \mathbf{1}$$

of $\alpha(t, \theta)$ exist? First observe that

$$\left(\frac{\partial}{\partial t} + \omega \cdot \nabla_{\theta}\right)\alpha(t, \theta) = \alpha(t, \theta)\beta(\theta), \quad \alpha(0, 0) = \mathbf{1},$$

where $\beta_k(\theta) = e^{ik \cdot \theta}$ and $\beta_w(\theta) = 0$ for $w = k_1 \cdots k_r$ with $r > 1$.

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Sketch of proof: We first show that $\exists \kappa(\theta), \bar{\beta}$ such that

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B-series expansion of exact solution of quasi-periodic ODEs

$$y(t) = B(\alpha(t), y_0), \quad \text{where} \quad \alpha_u(t) = \alpha_u(t, \theta(t)) = \sum_{w \in \mathcal{W}_u} \alpha_w(t, \theta(t)).$$

Averaging formulae in B-series form

$$Y(t) = B(\bar{\alpha}(t), y_0), \quad \dot{Y} = B(\bar{\beta}, Y), \quad Y(t) = B(\kappa(\theta(t)), Y(t)),$$

- Quasi-stroboscopic averaging:

$$\bar{\alpha}(t) = \alpha(t, \theta_0), \quad \bar{\beta} = \left. \frac{d}{dt} \bar{\alpha}(t) \right|_{t=0}, \quad \kappa(\theta) = \alpha(0, \theta).$$

- Classical averaging:

$$\bar{\alpha}(t) = \int_{\mathcal{T}^d} \alpha(t, \theta) d\theta, \quad \bar{\beta} = \left. \frac{d}{dt} \bar{\alpha}(t) \right|_{t=0},$$
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Future work

- Prove rigorous results (bound independently the coefficients and the smooth y -dependent maps),
- Study approximate preservation of formal invariants of HOS,
- Analyze existing numerical methods for highly oscillatory systems
- Design and analyze new numerical methods. In particular, heterogeneous multiscale methods based on

microintegration+

numerical evaluation of averaged equations+

macrointegration

Algebraic/geometric properties of exact solution

For $u_1, u_2, u_3 \in \mathcal{T}$

- $\alpha_{u_1 \circ u_2} + \alpha_{u_2 \circ u_1} = \alpha_{u_1} \alpha_{u_2}$, \rightarrow symplectic for each fixed t, τ .
- In addition

$$\alpha_{u_1 \circ u_2 u_3} + \alpha_{u_2 \circ u_1 u_3} + \alpha_{u_3 \circ u_1 u_2} = \alpha_{u_1} \alpha_{u_2} \alpha_{u_3}.$$

Hence, for each fixed t, τ , it represents the 1-flow of a vector field in the Lie algebra generated by the f_k .

- Classical averaging does not preserve the properties of $\alpha(t, \tau)$:

$$\begin{aligned} & 1/(2\pi) \int_0^{2\pi} (\alpha_{u_1 \circ u_2}(t, \tau) + \alpha_{u_2 \circ u_1}(t, \tau)) d\tau \\ & \neq 1/(2\pi)^2 \left(\int_0^{2\pi} \alpha_{u_1}(t, \tau) d\tau \right) \left(\int_0^{2\pi} \alpha_{u_2}(t, \tau) d\tau \right) \end{aligned}$$

- Stroboscopic averaging: Properties inherited by $\bar{\alpha}(t) = \alpha(t, 0)$ (and $\bar{\beta}$). Stroboscopic averaging is well defined for periodic vector fields on manifolds.

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Algebraic/geometric properties of exact solution

For $u_1, u_2, u_3 \in \mathcal{T}$

- $\alpha_{u_1 \circ u_2} + \alpha_{u_2 \circ u_1} = \alpha_{u_1} \alpha_{u_2}$, \rightarrow symplectic for each fixed t, τ .
- In addition

$$\alpha_{u_1 \circ u_2 u_3} + \alpha_{u_2 \circ u_1 u_3} + \alpha_{u_3 \circ u_1 u_2} = \alpha_{u_1} \alpha_{u_2} \alpha_{u_3}.$$

Hence, for each fixed t, τ , it represents the 1-flow of a vector field in the Lie algebra generated by the f_k .

- Classical averaging does not preserve the properties of $\alpha(t, \tau)$:

$$\begin{aligned} & 1/(2\pi) \int_0^{2\pi} (\alpha_{u_1 \circ u_2}(t, \tau) + \alpha_{u_2 \circ u_1}(t, \tau)) d\tau \\ & \neq 1/(2\pi)^2 \left(\int_0^{2\pi} \alpha_{u_1}(t, \tau) d\tau \right) \left(\int_0^{2\pi} \alpha_{u_2}(t, \tau) d\tau \right) \end{aligned}$$

- Stroboscopic averaging: Properties inherited by $\bar{\alpha}(t) = \alpha(t, 0)$ (and $\bar{\beta}$). Stroboscopic averaging is well defined for periodic vector fields on manifolds.